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Synchronization and Deep Learning: Experiences Learned from Dataset Creation

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March 30, 2023

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Summary			

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- 2 Dataset Generation
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- 5 Results
- 6 Conclusion

Context ●000000	Learning and Classifying 00000		
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Context

PhD work of Cyrille Morin

- Main topic: on Deep Learning for radio
- Specific work: transmitter identification through radio fingerprinting
- Two objectives:
 - Construct a "good" dataset with Cognitive Radio Testbed (FIT/CorteXlab)
 - Test Deep Learning Convolutional Neural Network (CNN) models to fingerprint

Disclaimer!!

- Deep Learning for Radio \Rightarrow Not the holy grail!
- Choose your problems:
 - \blacksquare Many problems in communications have well behaved closed form solutions \Rightarrow no need for DL
 - Some problems are too difficult to model, or models are too complex or current tools are not adaptive \Rightarrow DL may help

Context			
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Transmitter Fingerprinting with Deep Learning

What is radio fingerprinting?

- Using the radio unique characteristics of the transmitters to tell them apart
- Radio's version of recognising the "voice" of familiar people on the phone
- Achieve radio identification in spite of the ID fields of packets!

Why do radio fingerprinting?

- IoT/small packet context
 - IoT based sensor networks: payload is of the same order of size as headers
 - High cost of header w.r.t. payload (energy and medium access)
 - Potential gains with TX identification based on radio fingerprinting

Security/privacy context

- Make ID spoofing harder :)
- Enable ID-field validation :)
- Track individual radios even if address is randomised :(

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(Identifiab	ole) Radio Charad	cteristics		

Base band

- Implementations of digital filters
- processing delays, jitter

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Intermediate Frequency

- Different sampling frequencies, digital-to-analog converters (linearity, resolution)
- Filters, amplifiers
- I/Q imbalance, DC offsets

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(Identifiable) Radio Characteristics

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Radio Frequency

- RF filter characteristics, RF amplifiers
- Local oscillator frequency offset, jitter, noise

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(Identifiable) Radio Characteristics

From Prior art

Channel effects [Xiao2009] [Xiao2009a]

- Channel effects dominate over RF signature
- Identification is restricted to propagation features: not robust

Power amplifier characteristics [Sankhe2018] and [Wong2018] [Hanna2018]

- Artificially manipulate the TX signals to exploit different characteristics
- Easy to impersonate
- Local oscillator imperfections [Hanna2018]

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Objectives			

The task at hand

- Identify 21 transmitters using an IoT like signal (USRP N2932 equiv. N210 with SBX)
- Use only raw IQ samples
- No channel equalization
- Produce a correctly labelled dataset devoid of channel bias (as much as we can)
- Test learning and generalisation ability

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FIT/CorteX	lab			



Characteristics

- Total of 42 radio nodes among USRPs N2932 and N2944R, PicoSDRs 2x2 and 4x4, Octoclocks for synchronization (USRPs only)
- Fully eletromagnetically isolated and semi-anechoised experimentation room (at least 60 dB of isolation)
- Robots for radio mobility
- Remote access operation, 100% automated experiment deployment

Dataset Generation •0000000	Learning and Classifying 00000		

Dataset Generation

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Overall structure



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Overall structure



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Transmi	ssion					
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Payload selection



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Frame				



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Reception and Labeling (Simplified)



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Reception and Labeling



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Recontion	and Labeling (z	oom)		



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Learning and Classifying

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Classification

Classifier and data

- Gold standard classifiers for fingerprinting: Convolutional Neural Networks (CNN)
- Used mainly for image recognition, due to its feature extraction capabilities
- Raw packet (600 samples) is used to construct an "image"
- $\blacksquare \text{ Complex samples} \Rightarrow$
 - Real part is encoded in first column
 - Imag part is encoded in second column
 - Rows are each sample of the packet

```
■ 2 × N<sub>samples</sub> "image"
```

Data handling

- \blacksquare 50000 \times 21 = 1050000 examples in one dataset
- Dataset examples split in 70% training, 10% validation and 20% test sets

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Neural network architecture



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Training and testing process

Training process

- Offline on a GPU server connected to FIT/CorteXlab
- 128 examples per batch
- More than 30 training epochs

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Generalisation capabilities



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Moving to multi-RX: three months of misery...

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Move to MultiRX

What we have done until now...

- Up to this point we were using node 6 as the RX
- High percentage accuracy on tests over the same training dataset (good)

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Need to add channel and receiver characteristics variations \Rightarrow MultiRX

- Create datasets with other receivers
- Combine all datasets into a big mixed dataset to mix all channels
- Provide generalisation with respect to receiver RF signature and channels

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Problem

Multi-RX datasets gave very poor performance!

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SingleRX tests, but this time done over more RXs

 \blacksquare Same: Training and testing on the same dataset works perfectly for the selected set of RXs \Rightarrow good

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Debugging			

- \blacksquare Exchange USRP devices that do not generalise \Rightarrow some replacements work, some others don't
- \blacksquare Hours and hours of analysis of hundreds of base band packets by eye \Rightarrow no visible differences

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Debugging			

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Could it be a sampling/synchronization problem?

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Facts

- Before starting the MultiRX tests the octoclocks were installed
- We turned on "external reference clock" on the basis of "it can not hurt to be synchronized"

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Testing th	ne hypothesis			

Disable "external reference clock" and repeat the generalisation tests \Rightarrow

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We verified the cable between the USRP and its octoclock \Rightarrow continuity issues

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Testing the hypothesis

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Final explanation

- The signal used to train is always sampled at the same rate (2 samples/syms) at the RX, but with:
 - A random initial sampling time for each transmission for unsynchronised nodes
 - A fixed and constant initial sampling time for each transmission for synchronized nodes

Which essentially means:

- A random initial sampling time for each transmission
 - \Rightarrow CNN learns to "ignore" sampling differences
- A fixed and constant initial sampling time for each transmission
 - \Rightarrow CNN learns one sampling and can not generalise to another sampling time

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Let's dig deeper...

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Sample time synchronisation

Accuracy over sampling time offset (upsampling \times 8)



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Sample time synchronisation

Accuracy over sample synchronisation offset (upsampling \times 8)



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Synced radio	Tx	Both	Rx	None
Tx	81.2%	34.5%	19.2%	38.3%
Both	54.4%	45.6%	38.2%	38.2%
Rx	21.1%	28.5%	80.2%	22.3%
None	41.3%	43.8%	34.6%	81.1%

Table: Accuracy of networks trained on one synchronisation possibility and tested on the others

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Conclusion

Takeaways

- Creating datasets for training DL for radio (or anything else) can be hard
- Seemingly innocuous parameters and settings can completely derail your DL system
- Datasets with raw I-Q samples: always check your clock source on UHD
 - Using PPS to synchronise time is probably OK
 - Using the 10 MHz REF signal to synchronise clock references should be carefully studied in your specific case
- Keep a logbook of important changes to your platforms if you're changing them while experimenting

If you want to explore further

- Full paper is online at: https://hal.inria.fr/hal-03117090/
- Datasets online at: https://wiki.cortexlab.fr/doku.php?id=tx-id
- FIT/CorteXlab wiki page: https://wiki.cortexlab.fr
- Next publication on this is coming soon...